Reconstruction formulas for Photoacoustic Imaging in Attenuating Media

Otmar Scherzer^{1,2} otmar.scherzer@univie.ac.at Cong Shi¹ cong.shi@univie.ac.at

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¹Computational Science Center University of Vienna Oskar-Morgenstern-Platz 1 A-1090 Vienna, Austria ²Johann Radon Institute for Computational and Applied Mathematics (RICAM) Altenbergerstraße 69 A-4040 Linz, Austria

Abstract

In this paper we study the problem of photoacoustic inversion in a *weakly* attenuating medium. We present explicit reconstruction formulas in such media and show that the inversion based on such formulas is moderately ill–posed. Moreover, we present a numerical algorithm for imaging and demonstrate in numerical experiments the feasibility of this approach.

1 Introduction

When a probe is excited by a short electromagnetic (EM) pulse, it absorbs part of the EM-energy, and expands as a reaction, which in turn produces a pressure wave. In *photoacoustic experiments*, using measurements of the pressure wave, the ability of the medium to transfer absorbed EM-energy into pressure waves is visualized and used for diagnostic purposes. Common visualizations, see [31], are based on the assumptions that the specimen can be *uniformly illuminated*, is acoustically *non-attenuating*, and that the *sound-speed* and *compressibility* are constant.

In mathematical terms, the photoacoustic imaging problem consists in calculating the compactly supported *absorption density function* $h : \mathbb{R}^3 \to$

 \mathbb{R} , appearing as a source term in the wave equation

$$\partial_{tt} p(t, \mathbf{x}) - \Delta p(t, \mathbf{x}) = \delta'(t) h(\mathbf{x}), \qquad t \in \mathbb{R}, \ \mathbf{x} \in \mathbb{R}^3, p(t, \mathbf{x}) = 0, \qquad t < 0, \ \mathbf{x} \in \mathbb{R}^3,$$
(1.1)

from some measurements over time of the pressure p on a two-dimensional manifold Γ outside of the specimen, that is outside of the support of the absorption density function. This problem has been studied extensively in the literature (see e.g. [17, 30, 16], to mention just a few survey articles).

Biological tissue has a non-vanishing viscosity, thus there is thermal consumption of energy. These effects can be described mathematically by *attenuation*. Common models of such are the *thermo-viscous* model [12], its modification [14], Szabo's power law [26, 25] and a causal modification [13], Hanyga & Seredy'nska [7], Sushilov & Cobbold [24], Ursin & Toverud [29] and the Nachman–Smith–Waag model [18]. Photoacoustic imaging in attenuating medium then consists in computing the absorption density function h from measurements of the attenuated pressure p^a on a surface containing the object of interest. The attenuated pressure equation reads as follows

$$\mathcal{A}_{\kappa}[p^{a}](t,\mathbf{x}) - \Delta p^{a}(t,\mathbf{x}) = \delta'(t)h(\mathbf{x}), \qquad t \in \mathbb{R}, \ \mathbf{x} \in \mathbb{R}^{3},$$
$$p^{a}(t,\mathbf{x}) = 0, \qquad t < 0, \ \mathbf{x} \in \mathbb{R}^{3},$$
(1.2)

where \mathcal{A}_{κ} is the pseudo-differential operator defined in frequency domain (see Equation 1.4). The formal difference between Equation 1.1 and Equation 1.2 is that the second time derivative operator ∂_{tt} is replaced by a pseudo-differential operator \mathcal{A}_{κ} .

The literature on photoacoustics in attenuating media concentrates on time-reversal and attenuation compensation based on power laws: We mention [3, 9, 10], and the k-wave toolbox implementation [4, 28]. Recently, also iterative methods [6] and Neumann series methods [21, 1] have been used for photoacoustic inversion in attenuating in media.

In [5] several attenuation laws from the literature have been cataloged into two classes, namely *weak* and *strong* attenuation laws. Power laws lead, in general, to severely ill-posed photoacoustic imaging problem, while mathematically sophisticatedly derived models, like the Nachman-Smith-Waag model [18], lead to moderately ill-posed problems.

The paper is based on the premise that photoacoustics is moderately ill– posed, and we therefore concentrate on photoacoustic inversion in weakly attenuating media, which have not been part of extensive analytical and numerical studies in the literature. Another goal of this work is to derive *explicit* reconstruction formulas for the absorption density function h in attenuating media. Previously there have been derived asymptotical expansions in the case of small absorbers [2, 11].

Notation

We use the following notations:

• For s = 0, 1, 2, ... we denote by $\mathcal{S}(\mathbb{R} \times \mathbb{R}^s)$ the Schwartz-space of complex valued functions and its dual space, the space of *tempered distribution*, is denoted by $\mathcal{S}'(\mathbb{R} \times \mathbb{R}^s)$.

We abbreviate $\mathcal{S} = \mathcal{S}(\mathbb{R} \times \mathbb{R}^3)$ and $\mathcal{S}' = \mathcal{S}'(\mathbb{R} \times \mathbb{R}^3)$.

• For $\phi \in \mathcal{S}(\mathbb{R})$ we define the Fourier-transform by

$$\hat{\phi}(\omega) = \frac{1}{\sqrt{2\pi}} \int_{t=-\infty}^{\infty} e^{i\omega t} \phi(t) dt,$$

and the one-dimensional inverse Fourier-transform is given by

$$\check{\varphi}(t) = \frac{1}{\sqrt{2\pi}} \int_{\omega=-\infty}^{\infty} e^{-\mathrm{i}\omega t} \varphi(\omega) \,\mathrm{d}\omega.$$

• Let $\varphi \in \mathcal{S}(\mathbb{R})$ and $\psi \in \mathcal{S}(\mathbb{R}^3)$. The Fourier-transform $\mathcal{F}[\cdot] : \mathcal{S}' \to \mathcal{S}'$ on the space of tempered distributions is defined by

$$\langle \mathcal{F}[u], \varphi \otimes \psi \rangle_{\mathcal{S}', \mathcal{S}} = \langle u, \check{\varphi} \otimes \psi \rangle_{\mathcal{S}', \mathcal{S}} \,. \tag{1.3}$$

Note that for functions $u \in \mathcal{S}$ we have

$$\langle \mathcal{F}[u], \varphi \otimes \psi \rangle_{\mathcal{S}', \mathcal{S}} = \int_{\mathbb{R} \times \mathbb{R}^3} u(t, \mathbf{x}) \overline{\check{\varphi}(t)\psi(\mathbf{x})} \, \mathrm{d}t \, \mathrm{d}\mathbf{x} \; .$$

We are identifying distributions and functions and we are writing in the following for all $u \in S'$

$$\mathcal{F}[u](\omega, \mathbf{x}) = \frac{1}{\sqrt{2\pi}} \int_{t=-\infty}^{\infty} e^{i\omega t} u(t, \mathbf{x}) dt \text{ and}$$
$$\mathcal{F}^{-1}[y](t, \mathbf{x}) = \frac{1}{\sqrt{2\pi}} \int_{\omega=-\infty}^{\infty} e^{-i\omega t} y(\omega, \mathbf{x}) d\omega.$$

• We define the attenuation operator $\mathcal{A}_{\kappa}[\cdot] : \mathcal{S}' \to \mathcal{S}'$ by

$$\langle \mathcal{A}_{\kappa}[u], \phi \otimes \psi \rangle_{\mathcal{S}',\mathcal{S}} = -\left\langle u, \widetilde{\kappa^2} \widehat{\phi} \otimes \psi \right\rangle_{\mathcal{S}',\mathcal{S}}.$$
 (1.4)

This means that if $u \in \mathcal{S}(\mathbb{R} \times \mathbb{R}^3)$ then

$$\mathcal{A}_{\kappa}[u](t,\mathbf{x}) = -\mathcal{F}^{-1}[\kappa^2 \mathcal{F}[u]](t,\mathbf{x}), \quad \omega \in \mathbb{R}, \ \mathbf{x} \in \mathbb{R}^3.$$
(1.5)

• $\mathcal{I}[\cdot]$ denotes the *time integration operator on the space of tempered distributions* and is given by

$$\langle \mathcal{I}[u], \phi \otimes \psi \rangle_{\mathcal{S}', \mathcal{S}} = - \langle u, \phi' \otimes \psi \rangle_{\mathcal{S}', \mathcal{S}},$$
 (1.6)

and we write formally for $u \in \mathcal{S}'$

$$u \to \mathcal{I}[u](t, \mathbf{x}) = \int_{-\infty}^{t} u(\tau, \mathbf{x}) d\tau.$$
(1.7)

• Equation 1.2 and Equation 1.1 (here $\kappa(\omega) = \omega^2$) are understood in a distributional sense, which means that for all $\phi \in \mathcal{S}(\mathbb{R})$ and $\psi \in \mathcal{S}(\mathbb{R}^3)$

$$\left\langle p^{a}, \widetilde{\kappa^{2}}\widehat{\phi} \otimes \psi \right\rangle_{\mathcal{S}', \mathcal{S}} + \left\langle p^{a}, \phi \otimes \Delta_{\mathbf{x}} \psi \right\rangle_{\mathcal{S}', \mathcal{S}}$$
$$= \phi'(0) \left\langle h, \psi \right\rangle_{\mathcal{S}'(\mathbb{R}^{3}), \mathcal{S}(\mathbb{R}^{3})} .$$
(1.8)

2 Attenuation

Attenuation describes the physical phenomenon that certain frequency components of acoustic waves are attenuated more rapidly over time. Mathematically this is encoded in the function κ defining the pseudo-differential operator \mathcal{A}_{κ} . A physically and mathematically meaningful κ has to satisfy the following properties (see [5]):

Definition 2.1 We call a non-zero function $\kappa \in C^{\infty}(\mathbb{R}; \overline{\mathbb{H}})$, where $\mathbb{H} = \{z \in \mathbb{C} : \Im m z > 0\}$ denotes the upper half complex plane and $\overline{\mathbb{H}}$ its closure in \mathbb{C} , an *attenuation coefficient* if

1. all the derivatives of κ are polynomially bounded. That is, for every $\ell \in \mathbb{N}_0$ there exist constants $\kappa_1 > 0$ and $N \in \mathbb{N}$ such that

$$\kappa^{(\ell)}(\omega)| \le \kappa_1 (1+|\omega|)^N, \tag{2.1}$$

2. There exists a holomorphic continuation $\tilde{\kappa} : \overline{\mathbb{H}} \to \overline{\mathbb{H}}$ of κ on the upper half plane, that is, $\tilde{\kappa} \in C(\overline{\mathbb{H}}; \overline{\mathbb{H}})$ with $\tilde{\kappa}|_{\mathbb{R}} = \kappa$ and $\tilde{\kappa} : \mathbb{H} \to \overline{\mathbb{H}}$ is holomorphic, and there exists constants $\tilde{\kappa}_1 > 0$ and $\tilde{N} \in \mathbb{N}$ such that

$$|\tilde{\kappa}(z)| \leq \tilde{\kappa}_1 (1+|z|)^N$$
 for all $z \in \overline{\mathbb{H}}$.

- 3. κ is symmetric: That is, $\kappa(-\omega) = -\overline{\kappa(\omega)}$ for all $\omega \in \mathbb{R}$.
- 4. There exists some constant c > 0 such that the holomorphic extension $\tilde{\kappa}$ of the attenuation coefficient κ satisfies

$$\Im(\tilde{\kappa}(z) - \frac{z}{c}) \ge 0$$
 for every $z \in \overline{\mathbb{H}}$.

Remark: The four conditions in Definition 2.1 on κ encode the following physical properties of the attenuated wave equation (see [5]):

- The condition Equation 2.1 in Definition 2.1 ensures that the product $\kappa^2 u$ of κ^2 with an arbitrary tempered distribution $u \in S'$ is again in S'and therefore, the operator $\mathcal{A}_{\kappa} : S' \to S'$ is well-defined on the space of tempered distributions.
- The second condition guarantees that the solution of the attenuated wave equation is causal.
- Condition three ensures that real valued distributions (such as the pressure) are mapped to real valued distributions. That is p^a is real valued if the absorption density h is real.
- The forth condition guarantees that the solution $p^a \in \mathcal{S}'(\mathbb{R} \times \mathbb{R}^3)$ of the equation Equation 1.2 propagates with finite speed c > 0. That is

$$\operatorname{supp} p^a \subset \{(t, x) \in \mathbb{R} \times \mathbb{R}^3 : |x| \le ct + R\}$$

whenever supp $h \subset B_R(0)$.

In the literature there have been documented two classes of attenuation models:

Definition 2.2 We call an attenuation coefficient $\kappa \in C^{\infty}(\mathbb{R}; \overline{\mathbb{H}})$ (see Definition 2.1)

• a weak attenuation coefficient if there exists a constant $0 \leq k_{\infty} \in \mathbb{R}$ and a bounded function $k_* \in C^{\infty}(\mathbb{R}; \mathbb{C}) \cap L^2(\mathbb{R}; \mathbb{C})$ such that

$$\kappa(\omega) = \omega + \mathrm{i}k_{\infty} + k_*(\omega) \text{ for all } \omega \in \mathbb{R}.$$
(2.2)

In particular, κ is constantly attenuating, if κ is a weak attenuation coefficient with $k_* \equiv 0$. That is, there exists a constant $k_{\infty} \geq 0$ such that

$$\kappa(\omega) = \omega + \mathrm{i}k_{\infty} \text{ for all } \omega \in \mathbb{R}.$$
(2.3)

• κ is called *strong attenuation coefficient* if there exist constants $\kappa_0 > 0$, $\beta > 0$, and $\omega_0 > 0$

$$\Im m \kappa(\omega) \ge \kappa_0 |\omega|^{\beta} \text{ for all } \omega \in \mathbb{R} \text{ with } |\omega| \ge \omega_0.$$
 (2.4)

For such attenuation coefficients we proved in [5] well-posedness of the attenuated wave equation:

Lemma 2.3 Let κ be an attenuation coefficient. Then the solution p^a of the equation Equation 1.2 exists and is a real-valued tempered distribution in $\mathbb{R} \times \mathbb{R}^3$.

Moreover, $q^a := \mathcal{I}[p^a]$ is a tempered distribution and satisfies the equation

$$\mathcal{A}_{\kappa}[q^{a}](t,\mathbf{x}) - \Delta q^{a}(t,\mathbf{x}) = \delta(t)h(\mathbf{x}), \qquad t \in \mathbb{R}, \ \mathbf{x} \in \mathbb{R}^{3}, q^{a}(t,\mathbf{x}) = 0, \qquad t < 0, \ \mathbf{x} \in \mathbb{R}^{3},$$
(2.5)

and in Fourier domain

$$\kappa^{2}(\omega)\mathcal{F}[q^{a}](\omega,\mathbf{x}) + \Delta_{\mathbf{x}}\mathcal{F}[q^{a}](\omega,\mathbf{x}) = -\frac{1}{\sqrt{2\pi}}h(\mathbf{x}).$$
(2.6)

Proof: The first item has been proven in [5]. The second item is an immediate consequence of the definition of a tempered distribution. \Box

Remark: Equation 2.5 has to be understood in a distributional sense: That is $q^a \in \mathcal{S}'$ and satisfies for every $\phi \in \mathcal{S}(\mathbb{R})$ and $\psi \in \mathcal{S}(\mathbb{R}^3)$ the equation

$$\langle \mathcal{A}_{\kappa}[q^{a}], \phi \otimes \psi \rangle_{\mathcal{S}', \mathcal{S}} - \langle q^{a}, \phi \otimes \Delta_{\mathbf{x}} \psi \rangle_{\mathcal{S}', \mathcal{S}} = \phi(0) \langle h, \psi \rangle_{\mathcal{S}'(\mathbb{R}^{3}), \mathcal{S}(\mathbb{R}^{3})}.$$
(2.7)

If $\kappa(\omega) = \omega$ (that is the case of the standard wave equation) $q = q^a$ solves the following equation in a distributional sense

$$\partial_{tt}q(t, \mathbf{x}) - \Delta_{\mathbf{x}}q(t, \mathbf{x}) = \delta(t)h(\mathbf{x}), \qquad t \in \mathbb{R}, \ \mathbf{x} \in \mathbb{R}^3, q(t, \mathbf{x}) = 0, \qquad t < 0, \ \mathbf{x} \in \mathbb{R}^3,$$
(2.8)

and its Fourier-transform $\mathcal{F}[q]$ satisfies the Helmholtz equation

$$\omega^{2} \mathcal{F}[q](\omega, \mathbf{x}) + \Delta_{\mathbf{x}} \mathcal{F}[q](\omega, \mathbf{x}) = -\frac{1}{\sqrt{2\pi}} h(\mathbf{x}), \quad \omega \in \mathbb{R}, \ \mathbf{x} \in \mathbb{R}^{3}.$$
(2.9)

Again $q \in \mathcal{S}'(\mathbb{R} \times \mathbb{R}^3)$ and satisfies Equation 2.8 in a distributional sense:

$$\langle q, \partial_{tt}\phi \otimes \psi \rangle_{\mathcal{S}',\mathcal{S}} - \langle q, \phi \otimes \Delta_{\mathbf{x}}\psi \rangle_{\mathcal{S}',\mathcal{S}} = \phi(0) \langle h, \psi \rangle_{\mathcal{S}'(\mathbb{R}^3),\mathcal{S}(\mathbb{R}^3)}.$$
 (2.10)

The solution of Equation 2.8 can also be written as the solution of the initial value problem:

$$\partial_{tt}q(t, \mathbf{x}) - \Delta_{\mathbf{x}}q(t, \mathbf{x}) = 0, \qquad t > 0, \ \mathbf{x} \in \mathbb{R}^{3},$$
$$q(0, \mathbf{x}) = 0, \qquad \mathbf{x} \in \mathbb{R}^{3},$$
$$(2.11)$$
$$\partial_{t}q(0, \mathbf{x}) = h(\mathbf{x}), \qquad \mathbf{x} \in \mathbb{R}^{3}.$$

In the following we derive a functional relation between q and q^a , which is the basis of analytical back-projection formulas in attenuating media.

Theorem 2.4 Let $\phi \in \mathcal{S}(\mathbb{R})$ and define

$$\nu_{+}[\phi](\tau) := \frac{1}{\sqrt{2\pi}} \int_{\omega=-\infty}^{\infty} e^{-i\overline{\kappa(\omega)}\tau} \hat{\phi}(\omega) \,\mathrm{d}\omega \text{ for all } \tau \ge 0 .$$

Then there exists a sequence $(a_m)_{m\geq 1}$ of real numbers satisfying $\sum_{m\geq 1} a_m 2^{mj} = (-1)^j$ and a function $\vartheta \in C_0^\infty(\mathbb{R};\mathbb{R})$ such that $\vartheta(\tau) = 1$ when $|\tau| < 1$ and $\vartheta(\tau) = 0$ when $|\tau| \geq 2$ such that the function $\nu : \mathbb{R} \to \mathbb{C}$, defined by

$$\nu(\tau) := \nu[\phi](\tau) := \begin{cases} \nu_+[\phi](\tau) & \text{for all} \quad \tau \ge 0, \\ \sum_{m=0}^{\infty} a_m \nu_+[\phi](-2^m \tau) \vartheta(-2^m \tau) & \text{for all} \quad \tau < 0, \end{cases}$$
(2.12)

is an element of the Schwartz space $\mathcal{S}(\mathbb{R})$.

Proof: 1. Using that for all $k \in \mathbb{N}_0$

$$\psi_k(\tau,\omega) := \partial_\tau^k e^{-i\overline{\kappa(\omega)}\tau} = (-i)^k \overline{\kappa(\omega)}^k e^{-i\overline{\kappa(\omega)}\tau} \text{ for all } \omega, \tau \in \mathbb{R},$$

it follows from Definition 2.2 that, uniformly in τ , for all $\omega \in \mathbb{R}$

$$\left|\psi_k(\tau,\omega)\hat{\phi}(\omega)\right| \leq |\kappa(\omega)|^k e^{-\Im m \kappa(\omega)\tau} \left|\hat{\phi}(\omega)\right| \leq |\kappa(\omega)|^k \left|\hat{\phi}(\omega)\right|.$$

From Equation 2.1 and $\hat{\phi} \in \mathcal{S}(\mathbb{R})$ (in particular $\kappa \in L^{\infty}(\mathbb{R}; \mathbb{C})$ and $\hat{\phi} \in C(\mathbb{R}; \mathbb{C})$), $\omega \to |\kappa(\omega)|^k |\hat{\phi}(\omega)| \in L^1(\mathbb{R}; \mathbb{R})$. Thus by interchanging integration and differentiation it follows that for $R \to \infty$

$$d^{k}\nu_{+}[\phi](\tau) = \frac{1}{\sqrt{2\pi}} \int_{\omega=-\infty}^{\infty} \psi_{k}(\tau,\omega)\hat{\phi}(\omega) \,\mathrm{d}\omega \text{ for all } \tau \ge 0 \qquad (2.13)$$

and that these functions are continuous. Thus $\nu_+[\phi] \in C^{\infty}([0,\infty); \mathbb{C})$.

- 2. From [22] it follows that $\nu[\phi]$ defined in Equation 2.12 is in $C^{\infty}(\mathbb{R}; \mathbb{C})$ and extends the function $\nu_{+}[\phi]$ defined on $[0, \infty)$.
- 3. We are proving that $\nu_+[\phi]$ and all its derivative are faster decaying than polynomials in τ for $\tau \to +\infty$.

For this purpose we use the *stationary phase method* summarized in Theorem A.1:

Let $\theta \in C_0^{\infty}(\mathbb{R};\mathbb{R})$ be a mollifier satisfying $\theta(\omega) = 1$ when $|\omega| < 1$ and $\theta(\omega) = 0$ when $|\omega| \ge 2$. For $k \in \mathbb{N}$ and R > 0 fixed, we apply the stationary phase method with

$$\omega \to f(\omega) = -\overline{\kappa(\omega)}$$
 and $\omega \to g_R(\omega) := \psi_k(\tau, \omega)\theta(\omega/R)$.

Below we are verifying the assumptions of the stationary phase method:

- $f \in C^{\infty}(\mathbb{R}; \mathbb{C})$ by Definition 2.1 and $g_R \in C_0^{\infty}(\mathbb{R}; \mathbb{C})$, because it is the product of a $C^{\infty}(\mathbb{R}; \mathbb{C})$ function and the compactly supported function $\omega \to \theta(\omega/R)$.
- The second property

$$\Im m f = \Im m \kappa \ge 0 . \tag{2.14}$$

is an immediate consequence of the assumption $\kappa \in C^{\infty}(\mathbb{R}; \overline{\mathbb{H}})$ in Definition 2.1.

Thus Equation A.1 can be applied with the functions $f = -\overline{\kappa}$ and g_R ,

and using Lemma A.2 Equation A.2 it follows that

$$\tau^{l} \left| \int_{\omega=-\infty}^{\infty} e^{i\tau f(\omega)} g_{R}(\omega) d\omega \right|$$

$$\leq C_{1} \sum_{\alpha=0}^{l} \sup_{\omega \in \mathbb{R}} |d^{\alpha} g_{R}(\omega)| \left(|f'(\omega)|^{2} + \Im f(\omega) \right)^{\alpha/2-l} \qquad (2.15)$$

$$\leq C_{1} \sum_{\alpha=0}^{l} \sup_{\omega \in \mathbb{R}} |d^{\alpha} g_{R}(\omega)| C_{2}^{\alpha/2-l}.$$

Next, we consider the limit $R \to \infty$. Because $\theta \in C_0^{\infty}(\mathbb{R}; \mathbb{R})$ and $g \in \mathcal{S}(\mathbb{R})$ and

$$d^{\alpha}g_{R}(\omega) = \sum_{\beta=0}^{\alpha} d^{\alpha-\beta}g(\omega) \binom{\alpha}{\beta} \frac{1}{R^{\beta}} d^{\beta}\theta(\omega),$$

it follows that

$$|d^{\alpha}g_{R}(\omega) - d^{\alpha}g(\omega)| \leq \left|\sum_{\beta=1}^{\alpha} d^{\alpha-\beta}g(\omega)\binom{\alpha}{\beta}\frac{1}{R^{\beta}}d^{\beta}\theta(\omega)\right| = \mathcal{O}(R^{-1}).$$

and from Equation 2.14 and the assumption $\tau \geq 0$ it follows

$$\left| \int_{\omega=-\infty}^{\infty} e^{i\tau f(\omega)} g_R(\omega) \, \mathrm{d}\omega - \int_{\omega=-\infty}^{\infty} e^{i\tau f(\omega)} g(\omega) \, \mathrm{d}\omega \right|$$
$$\leq \int_{\omega=-\infty}^{\infty} e^{-\tau \operatorname{\Im m} f(\omega)} |g_R(\omega) - g(\omega)| \, \mathrm{d}\omega \quad \leq \int_{\omega=-\infty}^{\infty} |g_R(\omega) - g(\omega)| \, \mathrm{d}\omega.$$

Using the definition of g_R it follows that

$$\int_{\omega=-\infty}^{\infty} |g_R(\omega) - g(\omega)| \, \mathrm{d}\omega \le \int_{\omega=-\infty}^{\infty} |g(\omega)| \, |1 - \theta(\omega/R)| \, \mathrm{d}\omega$$
$$\le \int_{|\omega|\ge R} |g(\omega)| \, \mathrm{d}\omega.$$

Since $g \in \mathcal{S}(\mathbb{R})$ the last integral tends to 0 for $R \to \infty$ and thus Equation A.1 holds even for the functions $\omega \to f(\omega) = -\overline{\kappa(\omega)}$ and $\omega \to g(\omega) = \psi_k(\tau, \omega)$, although they are not satisfying the assumptions of Theorem A.1. Because (according to Theorem 2.4), for every $\phi \in \mathcal{S}(\mathbb{R}), \nu[\phi] \in \mathcal{S}(\mathbb{R})$, the operator from the following definition is well-defined.

Definition 2.5 The attenuation solution operator $\mathcal{B}[\cdot] : \mathcal{S}' \to \mathcal{S}'$ is defined by

$$\langle \mathcal{B}[\rho], \phi \otimes \psi \rangle_{\mathcal{S}', \mathcal{S}} = \langle \rho, \nu[\phi] \otimes \psi \rangle_{\mathcal{S}', \mathcal{S}}$$
 for all $\rho \in \mathcal{S}'$ and $\phi \in \mathcal{S}(\mathbb{R}), \psi \in \mathcal{S}(\mathbb{R}^3)$. (2.16)

Remark: In a weakly attenuating medium $\kappa(\omega) = \omega + ik_{\infty} + k_*(\omega)$, and therefore, for every $t, \tau \in \mathbb{R}$

$$k(t,\tau) := \mathcal{F}^{-1}[e^{i(\cdot+i\kappa_{\infty}+k_{*}(\cdot))\tau}](t)$$

= $e^{-k_{\infty}\tau}\mathcal{F}^{-1}[e^{ik_{*}(\cdot)\tau}](t-\tau)$
= $e^{-k_{\infty}\tau}\mathcal{F}^{-1}[1+(e^{ik_{*}(\cdot)\tau}-1)](t-\tau)$
= $\sqrt{2\pi}e^{-k_{\infty}\tau}\delta(t-\tau) + e^{-k_{\infty}\tau}\mathcal{F}^{-1}[e^{ik_{*}(\cdot)\tau}-1](t-\tau).$ (2.17)

Because there exists a constant C > 0 such that

$$\left| e^{ik_*(\omega)\tau} - 1 \right| \le C \left| k_*(\omega)\tau \right| \text{ for all } \omega, \tau \in \mathbb{R},$$

it follows from Definition 2.2 (stating that $k_* \in L^2(\mathbb{R};\mathbb{C})$) and Plancharel's identity that

$$\begin{split} &\omega \to e^{\mathrm{i}k_*(\omega)\tau} - 1 \in L^2(\mathbb{R};\mathbb{C}) \text{ and} \\ &t \to e^{-k_{\infty}\tau}\mathcal{F}^{-1}[e^{\mathrm{i}k_*(\cdot)\tau} - 1](t-\tau) \in L^2(\mathbb{R};\mathbb{C}) \text{ for all } \tau \in \mathbb{R} \end{split}$$

Now, assume that $\rho \in C^0(\mathbb{R} \times \mathbb{R}^3; \mathbb{C}) \cap \mathcal{S}'$ with support in $[0, \infty) \times \mathbb{R}^3$, $\phi \in \mathcal{S}(\mathbb{R})$ and $\psi \in \mathcal{S}(\mathbb{R}^3)$

$$\begin{split} &\langle \rho, \nu[\phi] \otimes \psi \rangle_{\mathcal{S}',\mathcal{S}} \\ &= \int_{\mathbb{R}^3} \int_{\tau=-\infty}^{\infty} \rho(\tau, \mathbf{x}) \overline{\nu[\phi](\tau)\psi(\mathbf{x})} \, \mathrm{d}\tau \, \mathrm{d}\mathbf{x} \\ &= \frac{1}{\sqrt{2\pi}} \int_{\mathbb{R}^3} \overline{\psi(\mathbf{x})} \int_{\tau=-\infty}^{\infty} \rho(\tau, \mathbf{x}) \int_{\omega=-\infty}^{\infty} e^{\mathrm{i}\kappa(\omega)\tau} \hat{\overline{\phi}}(\omega) \, \mathrm{d}\omega \, \, \mathrm{d}\tau \, \mathrm{d}\mathbf{x} \end{split}$$

Using Parseval's identity we get

$$\langle \rho, \nu[\phi] \otimes \psi \rangle_{\mathcal{S}', \mathcal{S}}$$

$$= \frac{1}{\sqrt{2\pi}} \int_{\mathbb{R}^3} \int_{\tau=-\infty}^{\infty} \rho(\tau, \mathbf{x}) \overline{\psi(\mathbf{x})} \int_{t=-\infty}^{\infty} k(t, \tau) \overline{\phi(t)} \, \mathrm{d}t \, \mathrm{d}\tau \, \mathrm{d}\mathbf{x}$$

$$= \int_{\mathbb{R}^3} \int_{t=-\infty}^{\infty} \overline{\psi(\mathbf{x})\phi(t)} \underbrace{\left(\frac{1}{\sqrt{2\pi}} \int_{\tau=-\infty}^{\infty} k(t, \tau)\rho(\tau, \mathbf{x}) \, \mathrm{d}\tau\right)}_{=\mathcal{B}[\rho](t, \mathbf{x})} \, \mathrm{d}t \, \mathrm{d}\mathbf{x}.$$
(2.18)

Then for $\rho \in C^0(\mathbb{R} \times \mathbb{R}^3; \mathbb{C}) \cap S'$ it follows from Equation 2.18 and Equation 2.17 that

$$e^{k_{\infty}t}\mathcal{B}\left[\rho\right](t,\mathbf{x}) = (\mathcal{I}d + \mathcal{T})[\rho](t,\mathbf{x}), \qquad (2.19)$$

where

$$\mathcal{T}[\rho](t,\mathbf{x}) = \frac{1}{\sqrt{2\pi}} \int_{\tau=-\infty}^{\infty} e^{k_{\infty}(t-\tau)} \mathcal{F}^{-1}[e^{ik_{*}(\omega)\tau} - 1](t-\tau)\rho(\tau,\mathbf{x}) \,\mathrm{d}\tau \,. \quad (2.20)$$

Theorem 2.6 Let $q = \mathcal{I}[p]$ and $q^a = \mathcal{I}[p^a]$, where p and p^a are the solutions of the equations Equation 1.1 and Equation 1.2, respectively. Then

$$q^a = \mathcal{B}[q] \quad . \tag{2.21}$$

Proof: Let $\phi \in \mathcal{S}(\mathbb{R})$ and $\psi \in \mathcal{S}(\mathbb{R}^3)$. Then, from Equation 2.21, the definition of the Fourier-transform Equation 1.3, the definition of $\mathcal{B}[\cdot]$ in Equation 2.16, because $\nu[\phi] \in \mathcal{S}(\mathbb{R})$ (see Equation 2.12) and because q solves Equation 2.8 it follows that

$$\langle \mathcal{A}_{\kappa}[\mathcal{B}[q]], \phi \otimes \psi \rangle_{\mathcal{S}',\mathcal{S}} - \langle \mathcal{B}[q], \phi \otimes \Delta_{\mathbf{x}}\psi \rangle_{\mathcal{S}',\mathcal{S}}$$

$$= - \left\langle \mathcal{B}[q], \widetilde{\kappa^{2}\phi} \otimes \psi \right\rangle_{\mathcal{S}',\mathcal{S}} - \left\langle \mathcal{B}[q], \phi \otimes \Delta_{\mathbf{x}}\psi \right\rangle_{\mathcal{S}',\mathcal{S}}$$

$$= - \left\langle q, \nu \left[\widetilde{\kappa^{2}\phi} \right] \otimes \psi \right\rangle_{\mathcal{S}',\mathcal{S}} - \left\langle q, \nu[\phi] \otimes \Delta_{\mathbf{x}}\psi \right\rangle_{\mathcal{S}',\mathcal{S}}$$

$$= - \left\langle q, \nu \left[\widetilde{\kappa^{2}\phi} \right] \otimes \psi \right\rangle_{\mathcal{S}',\mathcal{S}} - \left\langle q, \partial_{\tau\tau}\nu[\phi] \otimes \psi \right\rangle_{\mathcal{S}',\mathcal{S}}$$

$$+ \nu[\phi](0) \left\langle h, \psi \right\rangle_{\mathcal{S}'(\mathbb{R}^{3}),\mathcal{S}(\mathbb{R}^{3})}$$

$$(2.22)$$

We are representing every term on the right hand side:

1. From Theorem 2.4 it follows that

$$\nu[\phi](0) = \frac{1}{\sqrt{2\pi}} \int_{\omega=-\infty}^{\infty} \hat{\phi}(\omega) \, \mathrm{d}\omega = \check{\phi}(0) = \phi(0)$$

and thus

$$\nu[\phi](0) \langle h, \psi \rangle_{\mathcal{S}'(\mathbb{R}^3), \mathcal{S}(\mathbb{R}^3)} = \phi(0) \langle h, \psi \rangle_{\mathcal{S}'(\mathbb{R}^3), \mathcal{S}(\mathbb{R}^3)}.$$

2. The first term on the right hand side of Equation 2.22 can be represented as follows:

$$\left\langle q, \nu\left[\widetilde{\kappa^{2}\hat{\phi}}\right] \otimes \psi \right\rangle_{\mathcal{S}', \mathcal{S}} = \left\langle q, \frac{1}{\sqrt{2\pi}} \int_{\omega=-\infty}^{\infty} \overline{\kappa^{2}(\omega)} e^{-\mathrm{i}\overline{\kappa(\omega)}} \hat{\phi}(\omega) \,\mathrm{d}\omega \otimes \psi \right\rangle_{\mathcal{S}', \mathcal{S}}.$$

3. For the second term we find that

$$\begin{split} \langle q, \partial_{\tau\tau} \nu[\phi] \otimes \psi \rangle_{\mathcal{S}',\mathcal{S}} &= \left\langle q, \frac{1}{\sqrt{2\pi}} \int_{\omega=-\infty}^{\infty} \partial_{\tau\tau} e^{-i\overline{\kappa(\omega)} \cdot} \hat{\phi}(\omega) \, \mathrm{d}\omega \otimes \psi \right\rangle_{\mathcal{S}',\mathcal{S}} \\ &= - \left\langle q, \frac{1}{\sqrt{2\pi}} \int_{\omega=-\infty}^{\infty} \overline{\kappa^2(\omega)} e^{-i\overline{\kappa(\omega)} \cdot} \hat{\phi}(\omega) \, \mathrm{d}\omega \otimes \psi \right\rangle_{\mathcal{S}',\mathcal{S}}. \end{split}$$

The sum of the first and second term vanishes and thus from Equation 2.22 it follows that

$$\langle \mathcal{A}_{\kappa}[\mathcal{B}[q]], \phi \otimes \psi \rangle_{\mathcal{S}', \mathcal{S}} - \langle \mathcal{B}[q], \phi \otimes \Delta_{\mathbf{x}} \psi \rangle_{\mathcal{S}', \mathcal{S}} = \phi(0) \langle h, \psi \rangle_{\mathcal{S}'(\mathbb{R}^3), \mathcal{S}(\mathbb{R}^3)} ,$$

which shows that $\mathcal{B}[q]$ solves Equation 2.7. Since the solution of this equation is unique it follows that $q^a = \mathcal{B}[q]$.

3 Reconstruction formulas

In this section we provide explicit reconstruction formulas for the absorption density h (the right hand side of Equation 1.2) in **attenuating** media. The basis of these formulas are exact reconstruction formulas in **non-attenuating** media.

In the case of non-attenuating media the problem of photoacoustic tomography consists in determining the absorption density h from measurement data of

$$m(t,\boldsymbol{\xi}) := p(t,\boldsymbol{\xi}) \text{ for all } t > 0, \boldsymbol{\xi} \in \Gamma,$$

where Γ denotes the measurement surface and p is the solution of Equation 1.1.

Let \mathcal{W} be the operator which maps h to p. The most universal (meaning applicable for a series of measurement geometries Γ) formula for $\mathcal{W}^{-1}[\cdot]$ is due to Xu & Wang [32]. Several different formulas of such kind were presented and analyzed in [17, 19, 15]. The formula of Xu & Wang [32] in \mathbb{R}^3 reads as follows:

$$h(x) = \frac{2}{\Omega_0} \int_{\boldsymbol{\xi} \in \Gamma} \frac{p(|\boldsymbol{\xi} - \mathbf{x}|, \boldsymbol{\xi}) - |\boldsymbol{\xi} - \mathbf{x}| \frac{\partial p}{\partial t}(|\boldsymbol{\xi} - \mathbf{x}|, \boldsymbol{\xi})}{|\boldsymbol{\xi} - \mathbf{x}|^2} \left(\mathbf{n}_{\boldsymbol{\xi}} \cdot \frac{\boldsymbol{\xi} - \mathbf{x}}{|\boldsymbol{\xi} - \mathbf{x}|} \right) \, \mathrm{d}s(\Gamma)$$
(3.1)

where Ω_0 is 2π for a planar geometry and 4π for cylindrical and spherical geometries and $\mathbf{n}_{\boldsymbol{\xi}}$ is the outer normal vector for the measurement surface Γ .

From Theorem 2.6 we get an explicit reconstruction formula in the case of attenuating media:

Theorem 3.1 Under the assumption that the universal back-projection can be applied in the non-attenuating case, we have

$$h = \mathcal{W}^{-1} \left[\partial_t \mathcal{B}^{-1} \left[(t, \boldsymbol{\xi}) \to q^a(t, \boldsymbol{\xi}) \right] \right].$$
(3.2)

In the following we study the attenuation operator $\mathcal{B}[\cdot]$ and its inverse in weakly attenuating media.

From Equation 2.19 it follows

$$h = \mathcal{W}^{-1} \left[\partial_t (\mathcal{I}d + \mathcal{T})^{-1} [(t, \boldsymbol{\xi}) \to e^{k_\infty t} q^a(t, \boldsymbol{\xi})] \right].$$
(3.3)

In particular, in the case of a constantly attenuating medium the kernel of the integral operator $\mathcal{B}[\cdot]$ simplifies to $(k_*(\omega) = 0)$

$$\frac{1}{\sqrt{2\pi}}\mathcal{F}^{-1}[e^{\mathrm{i}\kappa(\cdot)\tau}](t) = \frac{1}{\sqrt{2\pi}}e^{-k_{\infty}\tau}\mathcal{F}^{-1}[e^{\mathrm{i}\cdot\tau}](t) = e^{-k_{\infty}\tau}\delta(t-\tau).$$

Thus from Equation 2.18 it follows that

$$\mathcal{B}[q](t,\mathbf{x}) = \frac{1}{\sqrt{2\pi}} e^{-k_{\infty}t} q(t,\mathbf{x}) .$$
(3.4)

Thus the operator $\mathcal{B}[\cdot]$ is a multiplication operator and the reconstruction formula Equation 3.3 rewrites to

$$h = \mathcal{W}^{-1}\left[(t, \boldsymbol{\xi}) \to \partial_t \left(e^{k_\infty t} q^a(t, \boldsymbol{\xi})\right)\right].$$
(3.5)

Using that $q = e^{k_{\infty}t}q^a$, we get explicit formulas for the time derivatives of q:

$$\partial_t q(t, \boldsymbol{\xi}) = e^{k_\infty t} \left(k_\infty q^a(t, \boldsymbol{\xi}) + \partial_t q^a(t, \boldsymbol{\xi}) \right),$$

$$\partial_{tt} q(t, \boldsymbol{\xi}) = e^{k_\infty t} \left(k_\infty^2 q^a(t, \boldsymbol{\xi}) + 2k_\infty \partial_t q^a(t, \boldsymbol{\xi}) + \partial_{tt} q^a(t, \boldsymbol{\xi}) \right).$$

Therefore, inserting the representation of the derivatives in Equation 3.1 we get

$$\begin{aligned}
\tilde{q}^{a}(t,\boldsymbol{\xi}) &= \partial_{t} q^{a}(t,\boldsymbol{\xi}) - t \partial_{tt} q^{a}(t,\boldsymbol{\xi}) ,\\
h(\mathbf{x}) &= \frac{2}{\Omega_{0}} \int_{\boldsymbol{\xi} \in \Gamma} \frac{\tilde{q}^{a}(|\boldsymbol{\xi} - \mathbf{x}|, \boldsymbol{\xi})}{|\boldsymbol{\xi} - \mathbf{x}|^{2}} \left(\mathbf{n}_{\boldsymbol{\xi}} \cdot \frac{\boldsymbol{\xi} - \mathbf{x}}{|\boldsymbol{\xi} - \mathbf{x}|} \right) \, \mathrm{d}s(\Gamma).
\end{aligned}$$
(3.6)

4 Numerical experiments

In this section we describe an algorithm for photoacoustic inversion in a weakly attenuating medium, in which case the attenuation coefficient is $\omega \to \kappa(\omega) = \omega + ik_{\infty} + k_*(\omega)$, with $k_* \in L^2(\mathbb{R}; \mathbb{C}) \cap C^{\infty}(\mathbb{R}; \mathbb{C})$.

The numerical inversions and examples will be performed in \mathbb{R}^2 for the two-dimensional attenuated wave equation. This is consistent with a distributional solution of Equation 1.2 in \mathbb{R}^3 where $(x, y, z) \to h(x, y)$ is considered a distribution in \mathbb{R}^3 , which is independent of the third variable. In this case p^a can be considered a two-dimensional distribution Equation 1.2, which solves the two-dimensional attenuated wave equation:

$$\mathcal{A}_{\kappa}[p^{a}](t, x_{1}, x_{2}) - \Delta p^{a}(t, x_{1}, x_{2}) = \delta'(t)h(x_{1}, x_{2}), \qquad t \in \mathbb{R}, \ (x_{1}, x_{2}) \in \mathbb{R}^{2},$$
$$p^{a}(t, x_{1}, x_{2}) = 0, \qquad t < 0, \ (x_{1}, x_{2}) \in \mathbb{R}^{2}.$$
$$(4.1)$$

The two-dimensional universal back-projection formula from [3], which is used below, is given by

$$h(x) = -\frac{4}{\Omega_0} \int_{\boldsymbol{\xi} \in \Gamma} \int_{t=|\boldsymbol{\xi} - \mathbf{x}|}^{\infty} \left(\frac{(\partial_t (t^{-1}p))(t, \boldsymbol{\xi})}{\sqrt{t^2 - |\boldsymbol{\xi} - \mathbf{x}|^2}} \, \mathrm{d}t \right) \mathbf{n}_{\boldsymbol{\xi}} \cdot (\boldsymbol{\xi} - \mathbf{x}) \, \mathrm{d}s(\Gamma), \qquad (4.2)$$

where Ω_0 is 2π for a line measurement geometry and 4π for a circular measurement geometry, $\mathbf{n}_{\boldsymbol{\xi}}$ is the outer normal vector for the curve Γ .

We assume that the attenuated photoacoustic pressure p^a is measured on a set of N points on a measurement curve Γ at N_T uniformly distributed time points

$$t_i = i\Delta_T, \ i = 1, \dots, N_T \text{ where } \Delta_T = \frac{T}{N_T}.$$

In our experiments Γ will either be a circle of radius R, where the N measurement points are radially uniformly distributed,

$$\boldsymbol{\xi}_j = R(\cos(j\Delta_{\boldsymbol{\xi}}), \sin(j\Delta_{\boldsymbol{\xi}})), \ j = 0, 1, \dots, N-1 \text{ where } \Delta_{\boldsymbol{\xi}} = \frac{2\pi}{N}$$

or on a segment of length 2l of the x-axis, in which case

$$\boldsymbol{\xi}_j = (2j\Delta_x - 1, 0), \text{ where } \Delta_x = l/N.$$

In this case we consider h to be supported in the upper half-space.

The evaluation of the integral operator $\mathcal{I}[.]$ is numerically realized as follows: For every measurement point $\{\boldsymbol{\xi}_j : j = 0, 1, \dots, N-1\}$

$$q^{a}(t_{i}, \boldsymbol{\xi}_{j}) = \Delta_{T} \sum_{n=1}^{i} p^{a}(t_{n}, \boldsymbol{\xi}_{j}).$$
(4.3)

The relation $q^a = \mathcal{B}[q]$ from Equation 2.21 is realized numerically as follows: Because we assume a weakly attenuation medium $\mathcal{B}[\cdot]$ (defined in Equation 2.16) is an integral operator with kernel k defined in Equation 2.17. We use the Taylor-series expansion of the exponential function $\tau \to e^{ik_*(\omega)\tau}$ and get

$$\mathcal{F}^{-1}[e^{ik_*(\omega)\tau} - 1](t) = \sum_{k=1}^{\infty} \frac{\tau^k}{k!} \mathcal{F}^{-1}[(ik_*(\omega))^k](t).$$
(4.4)

Inserting Equation 4.4 into Equation 2.20 and taking into account Equation 2.19 and Equation 2.21 we get for all $i = 1, ..., N_T$ that

$$q^{a}(t_{i},\boldsymbol{\xi}_{j}) = e^{-k_{\infty}t_{i}}q(t_{i},\boldsymbol{\xi}_{j}) + \frac{1}{\sqrt{2\pi}}\int_{\tau=-\infty}^{\infty} e^{-k_{\infty}\tau}\sum_{k=1}^{\infty}\frac{\tau^{k}}{k!}r_{k}(t_{i}-\tau)q(\tau,\boldsymbol{\xi}_{j})\,\mathrm{d}\tau, \qquad (4.5)$$

where

$$s \to r_k(s) := \mathcal{F}^{-1}[\mathrm{i}^k k^k_*(\omega)](s).$$

The integral on the right hand side of Equation 4.5 is approximated for numerical purposes as follows:

$$\frac{\Delta_T}{\sqrt{2\pi}} \sum_{m=1}^{N_T} e^{-k_\infty t_m} \sum_{k=1}^{\infty} \frac{t_m^k}{k!} r_k(t_i - t_m) q(t_m, \boldsymbol{\xi}_j).$$
(4.6)

This expression is represented as a matrix-vector multiplication with vector $\vec{q}_j = (q(t_m, \boldsymbol{\xi}_j))_{m=1,\dots,N_T}$ and matrix with entries

$$b_{im} = \frac{\Delta_T}{\sqrt{2\pi}} e^{-k_\infty t_m} \sum_{k=1}^{\infty} \frac{t_m^k}{k!} r_k (t_i - t_m) \text{ with } 1 \le i \le N_T, \text{ and } 1 \le m \le N_T.$$
(4.7)

Then it follows from Equation 4.5 that

$$\bar{q}_j^a = (\operatorname{diag} e^{-k_\infty t_i} + B) \bar{q}_j , \qquad (4.8)$$

which is the discretized version of Equation 2.19. To get numerical values for the entries of B, the terms $r_k(t_i - t_m)$ have to be numerically calculated. For k = 1,

$$r_1(t) = \frac{1}{\sqrt{2\pi}} \int_{\omega = -\infty}^{\infty} ik_*(\omega) e^{-i\omega t} d\omega, \qquad (4.9)$$

which can be evaluated by numerical integration for all t_i . When k > 1, r_k is a convolution of r_{k-1} and r_1 and thus

$$r_k(t) = \frac{1}{\sqrt{2\pi}} (r_1 * r_{k-1})(t) = \frac{1}{\sqrt{2\pi}} \int_0^t r_1(\tau) r_{k-1}(t-\tau) \,\mathrm{d}\tau.$$
(4.10)

Numerically, we approximate the convolution by

$$r_k(t_i) \approx \frac{\Delta_T}{\sqrt{2\pi}} \sum_{m=1}^i r_1(t_m) r_{k-1}(t_i - t_m).$$

We summarize the inversion process in a pseudo-code, where we truncate the Taylor-series Equation 4.4 at the tenth coefficient (the number ten has been found from numerical simulations): **Data:** The measurements are denoted by $P_{i,j}^a = p^a(t_i, \boldsymbol{\xi}_j)$ for all $i = 1, \dots, N_T$ and $j = 0, \dots, N-1$

Result: Numerical calculation of the absorption density $h_l = h(x_l)$ for $1 \le i \le N_T$ do

$$r_{i,1} \leftarrow \frac{1}{\sqrt{2\pi}} \int_{\omega = -\infty}^{\infty} e^{-\mathrm{i}\omega t_i} (\mathrm{i}k_*(\omega)) \,\mathrm{d}\omega;$$

end

for $1 \le k \le 10$ do for $1 \le m \le n \le N_T$ do $| (F_k)_{i,m} \leftarrow \frac{1}{\sqrt{2\pi}} r_{i-m,k} t_m^k e^{-k_\infty t_m};$ end for $1 \le i \le N_T$ do $| r_{i,k+1} = \frac{\Delta_T}{\sqrt{2\pi}} \cdot (\sum_{m=1}^i r_{m,k} r_{i-m,k});$ end end $R \leftarrow \operatorname{diag}(e^{-k_\infty t_1}, e^{-k_\infty t_2}) + \Delta_T \sum^{10}$

 $\begin{array}{l} B \leftarrow \operatorname{diag}(e^{-k_{\infty}t_{1}}, e^{-k_{\infty}t_{2}}, \dots) + \Delta_{T} \sum_{k=1}^{10} \frac{F_{k}}{k!};\\ \mathbf{for} \ 1 \leq i \leq N_{T} \ \mathbf{do} \\ \mid \ Q_{i,j}^{a} \leftarrow Q_{i-1,j}^{a} + \Delta_{T} P_{i,j}^{a};\\ \mathbf{end} \\ Q \leftarrow Q^{a} B^{-1};\\ \mathbf{for} \ 1 \leq i \leq N_{T} \ \mathbf{do} \\ \mid \ P_{i,j} \leftarrow \frac{Q_{i,j} - Q_{i-1,j}}{\Delta_{T}};\\ \mathbf{end} \\ \mathrm{Calculate} \ h_{l} \ \mathrm{by} \ \mathrm{applying} \ \mathrm{the} \ \mathrm{back-projection} \ \mathrm{operator} \ \mathcal{W}^{-1} \left[\cdot\right] \ \mathrm{on} \end{array}$

Algorithm 1: Pseudocode for reconstructing the absorption density h.

Numerical experiments

 $P_{i,i};$

We assume that h is a function with compact support in \mathbb{R}^2 . We calculated p, the solution of Equation 1.1 using the k-wave toolbox [27]. By integrating p at the points $\boldsymbol{\xi}_j$, $j = 0, \ldots, N-1$ over time with Equation 4.3 we get $q(t_i, \boldsymbol{\xi}_j)$ for $i = 1, \ldots, N_T$ and $j = 0, \ldots, N-1$. Then we find $q^a(t_i, \boldsymbol{\xi}_j)$ by matrix-vector multiplication Equation 4.8.

In order to avoid *inverse crimes* we used different discretization points in space and time for the simulation of the forward data and the inversion. The forward problem is simulated with $N_T = 500$ and N = 896, while the inverse problem is solved with $N_T = 443$ and N = 849. The absorption density function $h : \mathbb{R}^2 \to \mathbb{R}$ with support in $(-0.8, 0.8)^2$ is the SheppLogan phantom [23]. In all numerical experiments the material parameter $k_{\infty} = 0.45$.

Circular measurement geometry

In these examples the measurement geometry is a circle with radius R = 1.7 on which there are recorded data on N = 849 uniformly distributed measurement points. Moreover, the time length is 6 and thus $\Delta_T = 6/N_T = 6/443$.

We consider a constantly attenuating medium, with attenuation coefficient $\kappa(\omega) = \omega + ik_{\infty}$. Figure 1 shows the ground truth (top left) and the simulated pressure data p^a on Γ over time. Two reconstructions are presented: The first one is obtained by applying the universal back-projection formula Equation 4.2 (middle left), while the middle right image shows the reconstruction obtained with Algorithm 1. The quantitative values of ground truth and the two reconstructions are plotted on the bottom.

Next we consider the Nachman, Smith and Waag (NSW) [18] attenuation model:

$$\kappa(\omega) = \omega \sqrt{\frac{1 - \mathrm{i}\omega\tilde{\tau}}{1 - \mathrm{i}\omega\tau}} = \omega + \frac{\tau - \tilde{\tau}}{2\tau\tilde{\tau}} \mathrm{i} + k_*(\omega)$$
(4.11)

where $k_*(\omega) = \mathcal{O}(|\omega|^{-1})$. Therefore, κ is a weak attenuation coefficient with $k_{\infty} = \frac{\tau - \tilde{\tau}}{2\tau \tilde{\tau}}$. In Figure 2 we present ground truth, simulated measurements p^a , and compare three imaging techniques:

- Applying the universal back-projection formula $\mathcal{W}^{-1}[p^a]$ Equation 4.2 (thus neglecting the attenuation).
- The compensated back-projection formula

$$\mathcal{W}^{-1}\left[(t,\boldsymbol{\xi})\mapsto\partial_t\left(e^{k_\infty t}q^a(t,\boldsymbol{\xi})\right)\right],\tag{4.12}$$

which neglects $k_*(\omega)$ but takes into account k_{∞} .

• Reconstruction using Equation 3.2 with the numerical code described in Algorithm 1.

The parameters of attenuation coefficient in the NSW model are $\tilde{\tau} = 0.1$ and $\tau = 0.11$. For small frequencies the NSW coefficients behaves like a power law of order 2. However, asymptotically, for large frequencies, it behaves like $\omega + \frac{\tau - \tilde{\tau}}{2\tau \tilde{\tau}}$ i. The NSW-coefficient has been plotted in Figure 3. In order to demonstrate the stability of the algorithm, we also performed reconstructions from noisy data, where, uniformly and identically distributed noise is added with maximal value equal to 20% of the maximal intensity at each measurement point. The reconstruction results are depicted in the last image of Figure 1 and Figure 2, respectively.



Figure 1: Measurements along a circle and constantly attenuating model. Row 1, Left: Ground truth. Row 1, Right: the simulated pressure data p^a . Rows 2 and 3: Reconstruction by universal back-projection (not taking into account attenuation), and by Algorithm 1 with noise-free data and 20% noise. Row 4: Cross section through ground truth and reconstructions.



Figure 2: Measurements along a circle and NSW model. Row 1, Left: Ground truth. Row 1, Right: the simulated pressure data p^a . Rows 2 and 3: Reconstruction by universal back-projection (not taking into account attenuation), by compensated attenuation Equation 4.12 and by Algorithm 1 with noise-free data and 20% noise. Row 4: Cross section through ground truth and reconstructions.



Figure 3: Blue curve corresponds to $\Im \kappa(\omega)$ of NSW model. Red curve corresponds to power law $0.005\omega^2$.

Concerning the stability of our algorithm, we notice that in all our numerical experiments the condition number of the matrix diag $e^{-k_{\infty}t_i} + B$ in Equation 4.8 is not too large, and does not exceed 200. Moreover, the condition number does not increase significantly when N_T increases. This means that the inversion of the matrix diag $e^{-k_{\infty}t_i} + B$ is quite stable.

Essentially the algorithm consist of the following two parts: In a first step the operator $\mathcal{B}^{-1}[\cdot]$ is applied to the data, which is followed by the backprojection. The first part is implemented as a matrix multiplication by $(\text{diag } e^{-k_{\infty}t_i} + B)^{-1}$. Numerical simulations show that this matrix multiplication is of negligible complexity compared to the backprojection part. Thus our algorithm has roughly the same complexity as the classical backprojection for no-attenuating media. The algorithm shown in [6] also has a similar complexity with ours (see Remark 3.2 in [6]). In our numerical experiments, the reconstruction process takes about 150 seconds.

For the resolution, from our reconstructions in Figures 1 and 2, we can see that our algorithm improves the image resolution compared with direct application of the universal back-projection algorithm and the compensated attenuation algorithm, as we see in rows 2 and 3 of Figures 1 and 2. Furthermore, compared with [6, 21] our algorithm achieves a similar level of image quality with a coarser discretization (the size of our figures is 200^2 pixels compared to $400^2 - 600^2$ pixels in [6, 21]).

Measurements on a line

The measurement points are N = 849 uniformly distributed on a line segment with length l = 10.2. The distance of the line to the center of the phantom is 1.7. The time length is 8 and thus $\Delta_T = 8/443$.

We consider a constantly attenuating medium, with attenuation coefficient $\kappa(\omega) = \omega + ik_{\infty}$. Figure 4 shows the ground truth (top left) and the

simulated pressure data p^a on Γ over time. Two reconstructions are presented: The first one is obtained by applying the universal back-projection formula Equation 4.2 (middle left) and the middle right image shows the reconstruction obtained with Algorithm 1. The quantitative values of ground truth and the two reconstructions are plotted on the bottom.

In Figure 5 we present ground truth, simulated measurements p^a using NSW model, and compare three imaging techniques, the universal backprojection formula neglecting attenuation, the compensated back-projection formula Equation 4.12, which neglects $k_*(\omega)$ but takes into account k_{∞} , and reconstruction with Algorithm 1. The parameters of the NSW attenuation coefficient are again $\tilde{\tau} = 0.1$ and $\tau = 0.11$. The reconstruction results from noisy data are depicted in the last image of Figure 4 and Figure 5, where uniformly distributed noise is added with a variance of 20% of the maximal intensity value. Numerical results show that the algorithm is quite stable even with 20% noise.



Figure 4: Measurements along a line and constantly attenuating model. Row 1, Left: Ground truth. Row 1, Right: the simulated pressure data p^a . Rows 2 and 3: Reconstruction by universal back-projection (not taking into account attenuation), and by Algorithm 1 with noise-free data and 20% noise. Row 4: Cross section through ground truth and reconstructions.



Figure 5: Measurements along a line and NSW model. Row 1, Left: Ground truth. Row 1, Right: the simulated pressure data p^a . Rows 2 and 3: Reconstruction by universal back-projection (not taking into account attenuation), by compensated attenuation Equation 4.12 and by Algorithm 1 with noise-free data and 20% noise. Row 4: Cross section through ground truth and reconstructions.

Conclusion

We have presented explicit reconstruction formulas for photoacoustic imaging in acoustically attenuating media, which are based on the universal backprojection formula. We have presented a numerical algorithm and showed numerical reconstructions, which were compared with attenuation compensation techniques. The numerical simulations show that the new technique can produce better visualization in 2D with a similar numerical complexity.

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A Appendix

Theorem A.1 [8, Section 7.7] Let $f, g \in C^{\infty}(\mathbb{R}; \mathbb{C})$ satisfying

- supp g is compact and
- $\Im m f(\omega) \ge 0.$

Then there exists a constant $C_1 > 0$ such that for all $l \in \mathbb{N}$ and all $\tau \ge 0$,

$$\tau^{l} \left| \int_{\omega=-\infty}^{\infty} e^{i\tau f(\omega)} g(\omega) d\omega \right|$$

$$\leq C_{1} \sum_{\alpha=0}^{l} \sup_{\omega \in \mathbb{R}} \left| d^{\alpha} g(\omega) \right| \left(|f'(\omega)|^{2} + \Im m f(\omega) \right)^{\alpha/2-l}.$$
(A.1)

Lemma A.2 Let κ be an attenuation coefficient (cf. Definition 2.1), then there exists a constant $C_2 > 0$ such that

$$\left|\kappa'(\omega)\right|^2 + \Im m \kappa(\omega) \ge C_2 . \tag{A.2}$$

Proof: The fourth assumption of Definition 2.1 ensures that the maximal speed of propagation c is finite. Then from [5, Proposition 2.9], it follows that the holomorphic extension $\tilde{\kappa}$ (cf. Definition 2.1) of κ to the upper half plane can be represented as

$$\tilde{\kappa}(z) = Az + B + \int_{\nu = -\infty}^{\infty} \frac{1 + z\nu}{\nu - z} \,\mathrm{d}\sigma(\nu), \quad z \in \mathbb{H},$$
(A.3)

where $A = \frac{1}{c} > 0, B \in \mathbb{R}$ are constants, and $\sigma : \mathbb{R} \to \mathbb{R}$ is a monotonically increasing function of bounded variation.

From [20, Formula (C9)] we know that if $\tilde{\kappa}$ satisfies Equation A.3, then

$$\nu \to \Im m \kappa(\nu) = \pi (1 + \nu^2) \sigma'(\nu) \text{ for all } \nu \in \mathbb{R} .$$
 (A.4)

Because, by assumption $\kappa \in C^{\infty}(\mathbb{R}; \mathbb{C})$, and because $\sigma : \mathbb{R} \to \mathbb{R}$ is a monotonically increasing function of bounded variation, we conclude from Equation A.4 that $\sigma' \in C^{\infty}(\mathbb{R}; \mathbb{R}) \cap L^1(\mathbb{R}; \mathbb{R})$. Moreover, for all fixed $z \in \mathbb{H}$, because $\nu - z \neq 0$ for all $\nu \in \mathbb{R}$, we have $\nu \to \frac{1+\nu^2}{(\nu-z)^2}$ is uniformly bounded and thus the function

$$u o rac{1+
u^2}{(
u-z)^2}\sigma'(
u) \in L^1(\mathbb{R};\mathbb{C})$$
 .

Differentiation of Equation A.3 with respect to z and taking into account that $\sigma' \in C^{\infty}(\mathbb{R}; \mathbb{R}) \cap L^1(\mathbb{R}; \mathbb{R})$ yields

$$\tilde{\kappa}'(z) = A + \int_{\nu = -\infty}^{\infty} \frac{(1+\nu^2)}{(\nu-z)^2} \sigma'(\nu) \,\mathrm{d}\nu, \quad z \in \mathbb{H}.$$

Let now $z = \omega + i\eta$ and take real parts in the above formula to get

$$\Re e \,\tilde{\kappa}'(\omega + i\eta) = A + \int_{\nu = -\infty}^{\infty} (1 + \nu^2) \frac{(\nu - \omega)^2 - \eta^2}{((\nu - \omega)^2 + \eta^2)^2} \sigma'(\nu) \,d\nu.$$
(A.5)

We are proving now that there exists a constant $C_r > 0$ such that

$$\Re e \,\kappa'(\omega) = \lim_{\eta \to 0^+} \Re e \,\tilde{\kappa}'(\omega + i\eta) \ge A - 2(1 + C_r)\sqrt{(1 + \omega^2)\sigma'(\omega)}.$$
(A.6)

Let

$$\begin{aligned} \mathcal{A}_+ &:= \left\{ \nu \in \mathbb{R} : |\nu - \omega|^2 \ge (1 + \omega^2) \sigma'(\omega) \right\}, \\ \mathcal{A}_- &:= \left\{ \nu \in \mathbb{R} : |\nu - \omega|^2 < (1 + \omega^2) \sigma'(\omega) \right\}, \\ \mathcal{A}_0 &:= \left\{ \hat{\nu} \in \mathbb{R} : |\hat{\nu}|^2 < (1 + \omega^2) \sigma'(\omega) \right\}. \end{aligned}$$

For $\omega \in \mathbb{R}$ and $\eta > 0$ let

$$\nu \to \rho_{\omega,\eta}(\nu) := (1+\nu^2) \frac{(\nu-\omega)^2 - \eta^2}{((\nu-\omega)^2 + \eta^2)^2} \sigma'(\nu) \text{ for all } \omega \neq \nu \in \mathbb{R}.$$

The function $\rho_{\omega,\eta}$ can be estimated as follows:

$$\rho_{\omega,\eta}(\nu) = \frac{1+\nu^2}{(\nu-\omega)^2 + \eta^2} \underbrace{\frac{(\nu-\omega)^2 - \eta^2}{(\nu-\omega)^2 + \eta^2}}_{\leq 1} \sigma'(\nu)$$

Moreover, since $\nu \in \mathcal{A}_+$, we find that

$$\frac{1+\nu^2}{(\nu-\omega)^2+\eta^2} \leq \frac{1+\nu^2}{(\nu-\omega)^2} = \underbrace{\frac{1+\nu^2}{1+(\nu-\omega)^2}}_{\leq 2(1+\omega^2)} \underbrace{\frac{1+(\nu-\omega)^2}{(\nu-\omega)^2}}_{\leq 1+((1+\omega^2)\sigma'(\omega))^{-1}},$$

where the inequality $\frac{1+\nu^2}{1+(\nu-\omega)^2} \leq 2(1+\omega^2)$ is a consequence of the algebraic identity $2(1+\omega^2)(1+(\nu-\omega)^2)-(1+\nu^2)=2\omega^2(\nu-\omega)^2+(\nu-2\omega)^2+1>0$. Therefore with $C_{\omega}=2(1+\omega^2)(1+((1+\omega^2)\sigma'(\omega))^{-1})$ it follows that

 $|\rho_{\omega,\eta}(\nu)| \le C_{\omega}\sigma'(\nu),$

and because $\sigma' \in L^1(\mathbb{R}; \mathbb{R})$ the latter means that the functions $\{\rho_{\omega,\eta} : \eta > 0\}$ are uniformly dominated by an $L^1(\mathbb{R}; \mathbb{R})$ function. Therefore we can apply the dominated convergence theorem and get

$$\lim_{\eta \to 0^+} \int_{\mathcal{A}_+} \rho_{\omega,\eta}(\nu) \, \mathrm{d}\nu = \int_{\mathcal{A}_+} \rho_{\omega,0}(\nu) \, \mathrm{d}\nu \ge 0.$$
(A.7)

To estimate $\int_{\mathcal{A}_{-}} \rho_{\omega,\eta}(\nu) \, d\nu$, we use the Taylor's expansion of $\omega \to (1 + (\hat{\nu} + \omega)^2)\sigma'(\hat{\nu} + \omega)$ and get

$$(1+(\hat{\nu}+\omega)^2)\sigma'(\hat{\nu}+\omega) = (1+\omega^2)\sigma'(\omega) + \hat{\nu}\left((1+\omega^2)\sigma''(\omega) + 2\omega\sigma'(\omega)\right) + r(\hat{\nu}),$$
(A.8)

with

$$|r(\hat{\nu})| \leq C_r \hat{\nu}^2$$
 for all $\hat{\nu} \in \mathcal{A}_-$

Using the substitution $\nu \rightarrow \hat{\nu} := \nu - \omega$ and Equation A.8 we get

$$\begin{split} &\lim_{\eta \to 0^{+}} \int_{\mathcal{A}_{-}} \rho_{\omega,\eta}(\nu) \, \mathrm{d}\nu \\ &= \lim_{\eta \to 0^{+}} \int_{\mathcal{A}_{0}} (1 + (\hat{\nu} + \omega)^{2}) \sigma'(\hat{\nu} + \omega) \frac{\hat{\nu}^{2} - \eta^{2}}{(\hat{\nu}^{2} + \eta^{2})^{2}} \, \mathrm{d}\hat{\nu} \\ &= (1 + \omega^{2}) \sigma'(\omega) \lim_{\eta \to 0^{+}} \int_{\mathcal{A}_{0}} \frac{\hat{\nu}^{2} - \eta^{2}}{(\hat{\nu}^{2} + \eta^{2})^{2}} \, \mathrm{d}\hat{\nu} \\ &+ \left((1 + \omega^{2}) \sigma''(\omega) + 2\omega \sigma'(\omega) \right) \lim_{\eta \to 0^{+}} \int_{\mathcal{A}_{0}} \hat{\nu} \frac{\hat{\nu}^{2} - \eta^{2}}{(\hat{\nu}^{2} + \eta^{2})^{2}} \, \mathrm{d}\hat{\nu} \\ &+ \lim_{\eta \to 0^{+}} \int_{\mathcal{A}_{0}} r(\hat{\nu}) \frac{\hat{\nu}^{2} - \eta^{2}}{(\hat{\nu}^{2} + \eta^{2})^{2}} \, \mathrm{d}\hat{\nu} \end{split}$$
(A.9)

Plugging in the integral formulas

$$\int_{-a}^{a} \frac{\nu^2 - \eta^2}{(\nu^2 + \eta^2)^2} \,\mathrm{d}\nu = \frac{-2a}{a^2 + \eta^2} \text{ and } \int_{-a}^{a} \nu \frac{\nu^2 - \eta^2}{(\nu^2 + \eta^2)^2} \,\mathrm{d}\nu = 0$$

into Equation A.9 we get for the first term with $a = \sqrt{(1 + \omega^2)\sigma'(\omega)}$

$$(1+\omega^{2})\sigma'(\omega)\lim_{\eta\to 0^{+}} \int_{\mathcal{A}_{0}} \frac{\hat{\nu}^{2}-\eta^{2}}{(\hat{\nu}^{2}+\eta^{2})^{2}} d\hat{\nu}$$

$$= (1+\omega^{2})\sigma'(\omega)\lim_{\eta\to 0^{+}} \frac{-2\sqrt{(1+\omega^{2})\sigma'(\omega)}}{(1+\omega^{2})\sigma'(\omega)+\eta^{2}} = -2\sqrt{(1+\omega^{2})\sigma'(\omega)},$$
(A.10)

and the second integral term in Equation A.9 is vanishing, and for the third term we get

$$\left| \int_{\mathcal{A}_0} r(\hat{\nu}) \frac{\hat{\nu}^2 - \eta^2}{(\hat{\nu}^2 + \eta^2)^2} \, \mathrm{d}\hat{\nu} \right| \le C_r \int_{\mathcal{A}_0} 1 \, \mathrm{d}\hat{\nu} \le 2C_r \sqrt{(1 + \omega^2)\sigma'(\omega)}. \tag{A.11}$$

Using the estimates Equation A.10 and Equation A.11 in Equation A.9 we get

$$\lim_{\eta \to 0^+} \int_{\mathcal{A}_-} \rho_{\omega,\eta}(\nu) \,\mathrm{d}\nu \ge -2(1+C_r)\sqrt{(1+\omega^2)\sigma'(\omega)}. \tag{A.12}$$

Considering the integral Equation A.5 as the sum of the two integrals over \mathcal{A}_{\pm} and using the estimates Equation A.7 and Equation A.12 we get

$$\lim_{\eta \to 0^+} \Re e \, \tilde{\kappa}'(\omega + i\eta) \ge A - 2(1 + C_r) \sqrt{(1 + \omega^2)\sigma'(\omega)}.$$

Therefore, $|\Re \epsilon \kappa'(\omega)| \ge \max(0, A - 2(1 + C_r)\sqrt{(1 + \omega^2)\sigma'(\omega)})$ and together with Equation A.4 it follows that

$$\begin{split} &|\kappa'(\omega)|^2 + \Im m \,\kappa(\omega) \\ \geq &\pi (1+\omega^2)\sigma'(\omega) + | \,\Re e \,\kappa'(\omega)|^2 \\ \geq &\pi (1+\omega^2)\sigma'(\omega) + \left(\max\left\{ 0, A - 2(1+C_r)\sqrt{(1+\omega^2)\sigma'(\omega)} \right\} \right)^2 \\ \geq & \underbrace{\frac{\pi A^2}{4(1+C_r)^2 + \pi}}_{:=C_2}, \end{split}$$

where in the last inequality we estimated the minimum of the quadratic function $\rho \to A^2 - 4A(1+C_r)\rho + (4(1+C_r)^2 + \pi)\rho^2$.